

F.T. of convolution of two signals

$$h(t) = f(t) * g(t)$$

$$H(\omega) = ?$$

$$h(t) = \int f(\tau) g(t-\tau) d\tau$$

$$H(\omega) = \int \int f(\tau) g(t-\tau) d\tau e^{-j\omega t} dt$$

$$= \int f(\tau) \int g(t-\tau) e^{-j\omega t} dt d\tau \quad (\text{reverse integrals})$$

$$\begin{aligned} q &= t - \tau \\ t &= q + \tau \\ dt &= dq \end{aligned}$$

$$= \int f(\tau) \int g(q) e^{-j\omega(q+\tau)} dq d\tau$$

$$= \int f(\tau) \left[ \int g(q) e^{-j\omega q} dq \right] e^{-j\omega\tau} d\tau$$

$$= \int f(\tau) G(\omega) e^{-j\omega\tau} d\tau$$

$$= G(\omega) \int f(\tau) e^{-j\omega\tau} d\tau$$

$$H(\omega) = G(\omega) F(\omega) //$$

## Properties of F.T.

$$f(at) \xleftrightarrow{F}$$

$$F(\omega) = \int f(at) e^{-j\omega t} dt$$

$$q = at \Rightarrow \frac{q}{a} = t$$

$$dq = a dt \Rightarrow dt = \frac{dq}{a}$$

$$\frac{1}{a} \int f(q) e^{-\frac{j\omega q}{a}} dq$$

$$\sigma = \frac{\omega}{a}$$

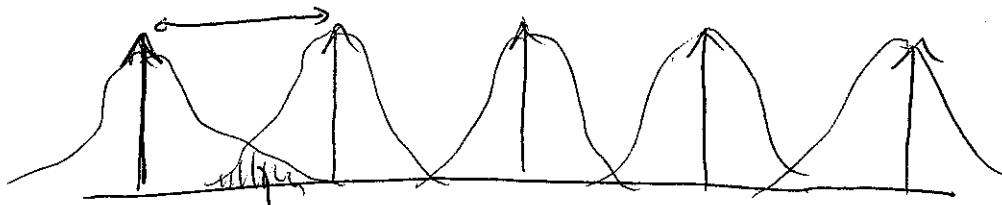
$$F = \frac{1}{a} F(\sigma) = \frac{1}{a} F\left(\frac{\omega}{a}\right)$$

## Aliasing

$$g(t) = f(t) \text{ sampled } \leftarrow \text{sample a continuous signal}$$

$$\Downarrow F$$

$$G(\omega) = \frac{1}{a} F(\omega) \sum_{k=-\infty}^{\infty} \delta\left(\frac{\omega}{a} - k\right) \leftarrow \text{this means replicas of } F(\omega) \text{ at each spike}$$



aliasing!

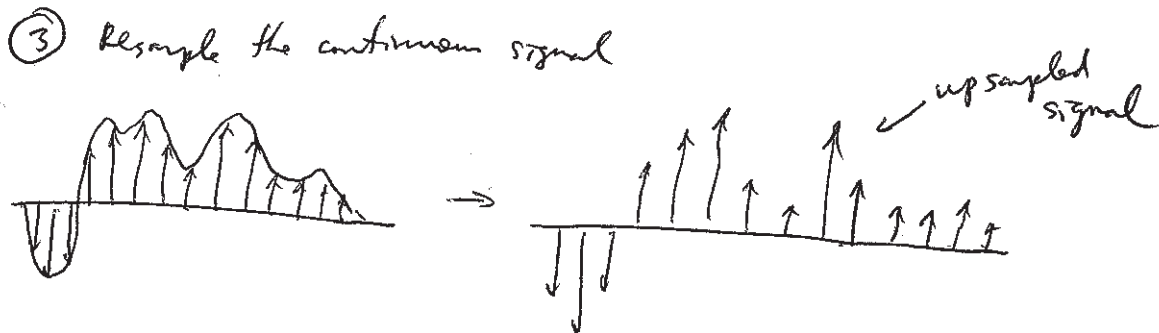
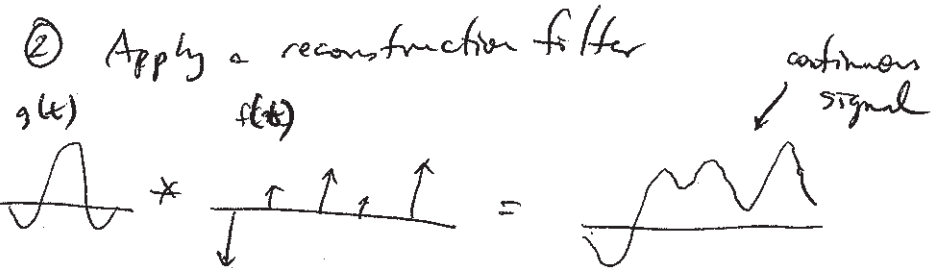
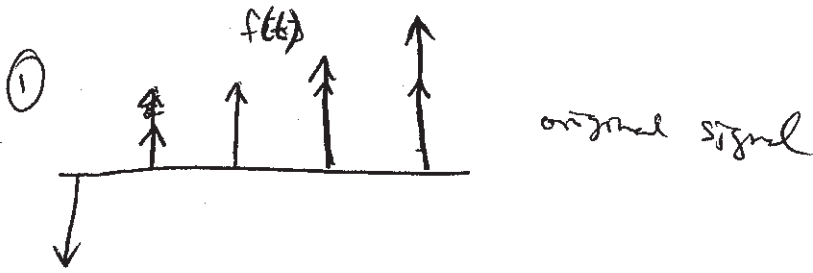
if  $F(\omega)$  has max frequency  $f_{max}$

then the sampling rate  $> 2f_{max}$  to avoid aliasing!

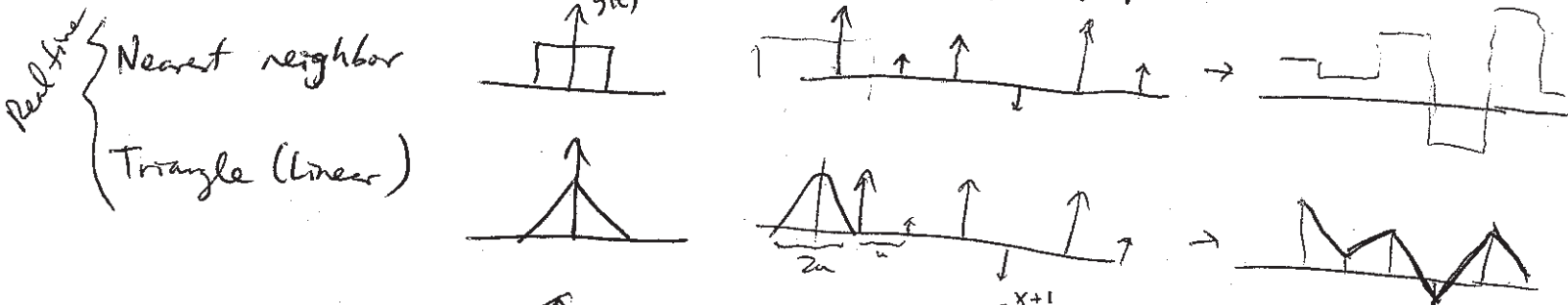
Down sampling - Reduce the number of samples in the image (decrease its resolution)

Up sampling - Increase the number of samples in the image (increase the resolution)

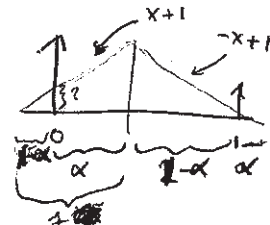
### Image Resampling



Common reconstruction filters used in ~~and~~ computer graphics



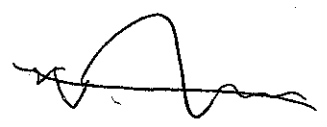
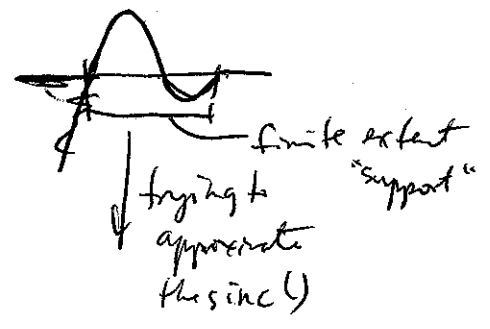
so linear blend: A B  
 $t = (1-\alpha)A + \alpha B$  is a line



$$\frac{1-\alpha}{f_1} = \frac{1}{1} \Rightarrow 1-\alpha = f_1$$

$$\frac{\alpha}{f_2} = 1 \Rightarrow \alpha = f_2$$

Bilinear



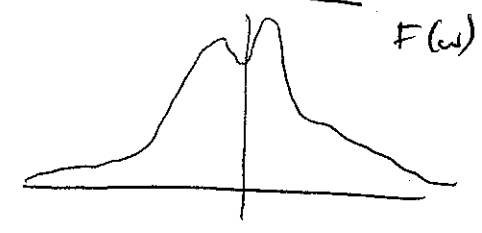
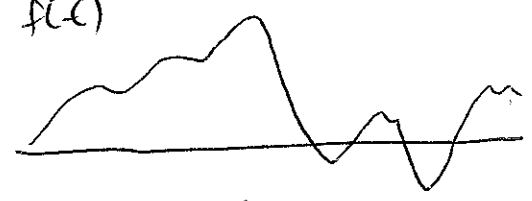
### Sampling and Resampling

SPATIAL DOMAIN

$\mathcal{F}$

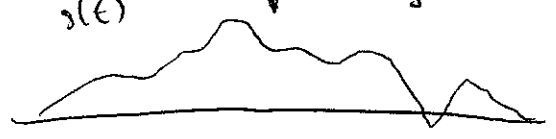
FREQUENCY DOMAIN

$f(x)$



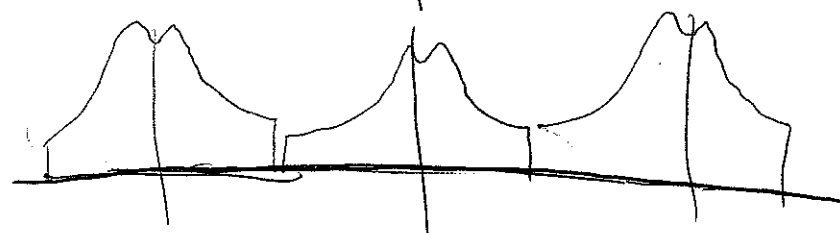
$s(x)$

↓ filtering

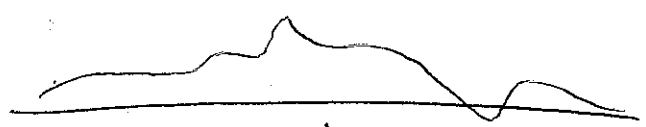


$h(x)$

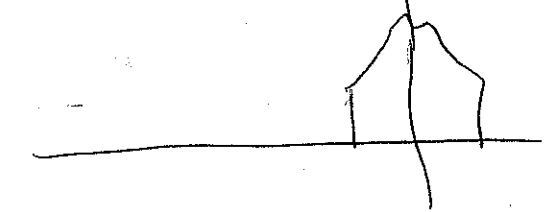
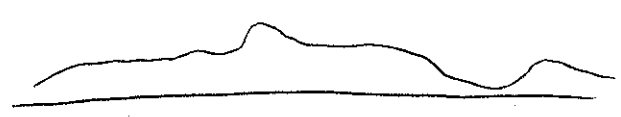
↓ sampling



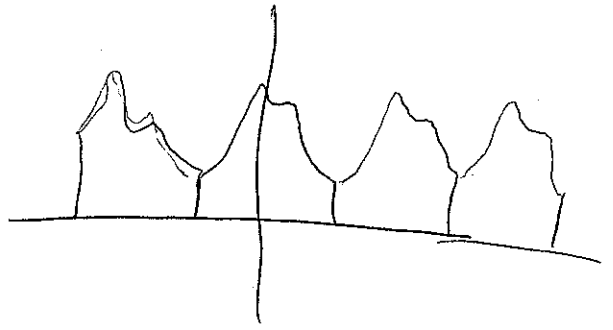
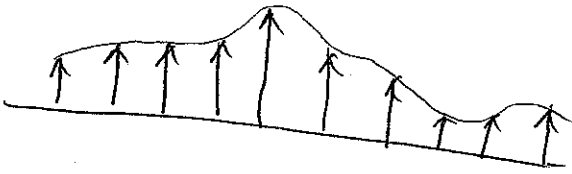
↓ reconstruction



↓ filtering



↓ resampling



In Rendering, we don't always have an analytical form for the expression  $f(t)$ .

How do you apply a filter so that you can sample?

- Super sampling!
1. Take a lot more samples
  2. Average them together to imitate a discrete filter.

