## Sensor and Simulation Notes

## Note

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Waveforms Near a Cylindrical Antenna by
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#### Abstract

The waveforms of the magnetic field are calculated and graphed at observation points close to, as well as far away from, an infinite cylindrical antenna excited by a step-function voltage across a circumferential gap of infinitesimal width. Analytical expressions for the early time and the late time behavior of the field are also derived. Precise criteria are given concerning the validity of some previous results obtained by performing an inverse Laplace transform on the time-harmonic far-field expression.


## I. Introduction

Recently we have presented some quantitative results on the radiation field of an infinite cylindrical antenna; loaded with either finite or zero resistance per unit length and excited by a step-function voltage across a delta gap. ${ }^{1,2}$ The method used in the previous calculations is first to make the far-zone approximation to the time-harmonic field and then to invert this far-field expression to the time domain. Although the results obtained via this method are, to be sure, correct for distances very far away from the antenna and for not too long an observation time, it is not clear precisely where and when the results do not hold. To settle this question we have to look for an expression for the field valid everywhere and for all time, and from this expression we can then deduce, analytically or numerically, some precise criteria for the validity of the previous results. This is one objective of this note.

The second objective of this note is to present some new results on the time behavior of the field near the antenna. These results should be valuable in the present development of an airborne EMP simulator.

One aspect of the present problem has been considered by $\mathrm{Wu}^{3}$; that is, he calculated the total current on an infinite cylindrical antenna excited by a step-function across a delta gap. Later, Morgan re-derived Wu's expression for the current by a different method. 4 Independently, Brundel1 5 studied the same problem with a treatment of the field included; however, he gave no quantitative results. The approach we shall use is slightly different from Brundell's, but much simpler. We shall numerically evaluate some derived formulas for the field and present some quantitative results in graphical form.

In Section II, we begin with a previously derived expression for the time-harmonic magnetic field and proceed to take its inverse Laplace transform for a step-function excitation. After several transformations of variables we arrive at a contour integral. This contour integral is then deformed, in Section III, into two different representations by a real integral, one of which is suitable for numerical computation. In Section IV, some limiting forms of the solution for small and large times are given, together with a few concluding remarks.

## II. Formulation

The time-harmonic magnetic field $\bar{H}_{\phi}$ of a perfectly conducting, infinite cylindrical antenna of radius $a$ and having $\widetilde{E}_{z}=-\widetilde{V} \delta(z)$ on its surface is given by ${ }^{2}$

$$
\begin{equation*}
\widetilde{H}_{\phi}(p, z)=\frac{i k \bar{V}}{2 \pi Z_{0}} \int_{-\infty}^{\infty} \frac{H_{1}^{(1)}\left(p\left(k^{2}-\zeta^{2}\right)^{1 / 2}\right)}{H_{0}^{(1)}\left(a\left(k^{2}-\zeta^{2}\right)^{1 / 2}\right)} \frac{e^{i \zeta z}}{\left(k^{2}-\zeta^{2}\right)^{1 / 2}} d \zeta \tag{1}
\end{equation*}
$$

The geometry and notation of the present problem are the same as in references 1 and 2 , and are depicted in Fig. 1.

Let $p=-i k$ and $\bar{V}=v_{0} /(p C)$, i.e., the excitation is a step function of voltage $v_{0}$. Then, the inverse Laplace transform of (1) gives

$$
\begin{equation*}
\frac{Z_{0} H_{\phi}(\rho, z, t)}{v_{0}}=\frac{1}{2 \pi i} \int_{C_{p}} e^{p c t} d p \cdot \frac{1}{2 \pi} \int_{-\infty}^{\infty} \frac{K_{1}(v \rho)}{\nu K_{0}(v a)} e^{i \zeta z} d \zeta \tag{2}
\end{equation*}
$$

where $v=\left(\zeta^{2}+p^{2}\right)^{1 / 2}$, the proper branch of which is defined in Fig. 2. In going from (1) to (2) we have used $\left(-\zeta^{2}-p^{2}\right)^{1 / 2}=i\left(\zeta^{2}+p^{2}\right)^{1 / 2}$, $H_{0}^{(1)}(i x)=-i(2 / \pi) K_{0}(x)$, and $H_{1}^{(1)}(i x)=-(2 / \pi) K_{1}(x)$. The paths of integration are shown in figures 2 and 3.

We now change the integral over $\zeta$ in equation (2) to that over $v$. First, let us determine the path of integration $C_{v}$ in the $v$-plane. Since $\zeta=\left(\nu^{2}-p^{2}\right)^{1 / 2}$, we must choose the branch of $\left(v^{2}-p^{2}\right)^{1 / 2}$ in the $v-p$ lane such that along $C_{v}$ we have
(i) $\zeta$ to be real in conformity with the path of the $\zeta$-integral,
(ii) Re $v \geq 0$ to guarantee damped waves for $\rho \rightarrow \infty$,
(iii) $\operatorname{Im} \zeta>0$ for $z>0$, and $\operatorname{Im} \zeta<0$ for $z<0$ so that the waves are damped for $|z| \rightarrow \infty$.
Now we write

$$
\begin{aligned}
\zeta & =\sqrt{\left(v_{1}+i \nu_{2}\right)^{2}-\left(p_{1}+i \dot{p}_{2}\right)^{2}} \\
& =\sqrt{\left(\overline{\nu_{1}^{2}}-v_{2}^{2}-p_{1}^{2}+p_{2}^{2}\right)+2 i\left(v_{1} \nu_{2}-p_{1} p_{2}\right)}
\end{aligned}
$$

To make $\zeta$ real along $C_{v}$ we must choose $C_{v}$ such that

$$
\begin{equation*}
v_{1} v_{2}=p_{1} P_{2} \tag{3a}
\end{equation*}
$$

and

$$
\begin{equation*}
v_{1}^{2}-v_{2}^{2}-p_{1}^{2}+p_{2}^{2} \geq 0 \tag{3b}
\end{equation*}
$$

Thus, $C_{v}$ must run alongside the part of hyperbolas (3a) where (3b) is satisfied and $v_{1} \geq 0$. Since $\zeta$ is positive real on one part of $C_{v}$ and negative real on the other part of $C_{V}$ (that is, the phase of $\zeta$ differs by $\pi$ in going from one part of the path to the other), there must be a branch cut ruming between the two parts of $C_{V}$. Hence, we arrive at Fig. 4 without the arrows, and the direction of $C_{v}$ is still to be determined. To determine the direction of $C_{v}$ we define the two branches of $\sqrt{\nu^{2}-p^{2}}$ as follows. The first branch is defined so that $\zeta=i p$ at $v=0$ and the second branch is defined so that $\zeta=-i p$ at $v=0$. Clearly, the first Riemann sheet maps into the upper $\zeta$-plane and the second sheet maps into the lower $\zeta$-pline. Then, in accordance with the condition (iii) we use the first branch for $z>0$ and the second branch for $z<0$. It is not difficult to see that the path $C_{v}$ depicted in Fig. 4 actually corresponds
to a path slightly displaced from the real $\zeta$-axis into the upper $\zeta$-plane. A path slightly displaced from the real 5 -axis into the lower $\zeta$-plane (for $z<0$ ) will transform into $C_{V}^{\prime}$ on the second Riemann sheet with direction opposite to $C_{V}$.

Under the transform $\zeta=\sqrt{v^{2}-p^{2}}$ we now can write (2) as follows:

$$
\begin{equation*}
\frac{z_{o} H_{\phi}}{v_{0}}=\frac{1}{2 \pi i} \int_{C_{p}} e^{p c t} d p \frac{1}{2 \pi} \int_{C_{\nu}} \frac{K_{1}(\nu p)}{K_{0}(v a)} \frac{e^{i \sqrt{\nu^{2}-p^{2} z}}}{\sqrt{\nu^{2}-p^{2}}} d \nu, \quad z>0 \tag{3}
\end{equation*}
$$

Since on the first Riemann sheet $\sqrt{\nu^{2}-p^{2}} \rightarrow \pm \nu$ as $|\nu| \rightarrow \infty$ in the first and fourth quadrant of the $v$-plane respectively, and since $K_{o}$ (va) has no zeros for $\mid$ arg $\nu \mid \leq \pi / 2$, we can deform $C_{v}$ into $\Gamma_{v}$ as shown in Fig. 4. Now the branch point $v=p$ always lies to the right of $\Gamma_{v}$ (that is to say, $\Gamma_{v}$ can be made independent of $p$ ) and, therefore, we can interchange the order of integration in (3) and obtain, with $\sqrt{v^{2}-p^{2}}=i \sqrt{2}-v^{2}$,

$$
\begin{align*}
& \frac{Z_{0} H_{\phi}}{v_{0}}=\frac{1}{2 \pi i} \int_{\Gamma_{\nu}} \frac{K_{1}(\nu \rho)}{K_{0}(v a)} d \nu \cdot \frac{1}{2 \pi i} \int_{C_{p}} \frac{e^{-\sqrt{p^{2}-v^{2}} z}}{\sqrt{v^{2}-v^{2}}} e^{p c t} d p \\
& =\frac{1}{2 \pi i} \int_{\Gamma_{\nu}} \frac{K_{1}(\nu \rho)}{K_{0}(v a)} I_{0}\left(\nu V(c t)^{2}-z^{2}\right) d v, \quad \text { for } \quad c t>z  \tag{4}\\
& \text { for ct < z } \\
& =0 \\
& \text { for ct < z }
\end{align*}
$$

where we have used a well-known result for the inner integral. ${ }^{6}$
The injegrand in (4) has no singularities to the right of $\Gamma_{\nu}$ (Fir. 5) and behaves as $\exp \left[-\nu\left(\rho-a-\sqrt{\left.(c t)^{2}-z^{2}\right)}\right]\right.$ as $|\nu| \rightarrow \infty$ in the right half plane. Thus, (4) gives

$$
\begin{equation*}
\frac{Z_{0} H_{\phi}}{v_{0}}=0, \quad \text { for } \quad c t<\sqrt{(p-a)^{2}+z^{2}} \tag{5}
\end{equation*}
$$

as it should.

## III. Solution

If. $\Gamma_{V}$ is deformed into the imaginary axis of the $v-p l a n e$ (Fig. 5) we have, noting that the integral around the branch point $v=0$ is zero,

$$
\begin{align*}
& \frac{Z_{0} H^{\prime} \phi}{v_{0}}=\frac{1}{2 \pi i} \int_{\Gamma} \frac{K_{1}(v 0)}{K_{0}(v a)} I_{0}(v \tau) d v \quad \tau=\left((c t)^{2}-z^{2}\right)^{1 / 2} \\
& =\frac{1}{2 \pi i} \int_{-i \infty}^{0} \frac{K_{1}(\nu \rho)}{K_{0}(v a)} I_{0}(\nu \tau) d \nu+\frac{1}{2 \pi i} \int_{0}^{i \infty} \frac{K_{1}(\nu \rho)}{K_{0}(v a)} I_{o}(\nu \tau) d \nu  \tag{6}\\
& =\frac{1}{2 \pi} \int_{-\infty}^{0} \frac{K_{1}\left(i v_{2} \rho\right)}{K_{0}\left(i \nu_{2} a\right)} I_{0}\left(i v_{2} \tau\right) d v_{2}+\frac{1}{2 \pi} \int_{0}^{\infty} \frac{K_{1}\left(i \nu_{2} \rho\right)}{K_{0}\left(i v_{2} a\right)} I_{0}\left(i v_{2} \tau\right) d v_{2} \\
& =-\frac{i}{2 \pi} \int_{0}^{\infty} \frac{H_{1}^{(2)}\left(\nu_{2} \rho\right)}{H_{0}^{(2)}\left(\nu_{2} a\right)} J_{0}\left(\nu_{2} \tau\right) d \nu_{2}+\frac{i}{2 \pi} \int_{0}^{\infty} \frac{H_{1}^{(1)}\left(\nu_{2} \rho\right)}{H_{0}^{(1)}\left(\nu_{2} a\right)} J_{0}\left(\nu_{2} \tau\right) d \nu_{2} \\
& =\frac{1}{\pi} \int_{0}^{\infty} \frac{J_{1}\left(v_{2} \rho\right) Y_{0}\left(\nu_{2} a\right)-J_{0}\left(\nu_{2} a\right) Y_{1}\left(\nu_{2} \rho\right)}{J_{0}^{2}\left(\nu_{2} a\right)+Y_{0}^{2}\left(v_{2} a\right)} J_{0}\left(\nu_{2}\left((c t)^{2}-z^{2}\right)^{1 / 2}\right) d v_{2} . \tag{7}
\end{align*}
$$

Setting $\rho=a$ in (7) we find that the total current $I(z, t)$ is given by

$$
\begin{equation*}
I(z, t)=2 \pi a H_{\phi}=\frac{4 v_{0}}{\pi Z_{0}} \int_{0}^{\infty} \frac{J_{0}\left(v_{2}\left((c t)^{2}-z^{2}\right)^{1 / 2}\right)}{J_{0}^{2}\left(v_{n} a\right)+Y_{0}^{2}\left(v_{2} a\right)} \frac{d v_{2}}{v_{2}} \tag{8}
\end{equation*}
$$

which is identical to Wu's expression. ${ }^{3}$
To obtain a form suitable for numerical integration we proceed as follows.

First, we substitute ${ }^{7} \pi i I_{0}(\nu \tau)=K_{0}(\nu \tau)-K_{0}\left(\nu \tau e^{i \pi}\right)$ and $\pi i I_{0}(\nu \tau)=$ $K_{0}\left(\nu \tau e^{-i \pi}\right)-K_{0}(\nu \tau)$ into the first and second integrals in (6) respectively and obtain

$$
\begin{align*}
\frac{z_{0} H_{\phi}}{v_{0}}= & -\frac{1}{2 \pi^{2}} \int_{-i \infty}^{0} \frac{K_{1}(v \rho)}{K_{0}(v a)}\left[k_{0}(v \tau)-K_{0}\left(v \tau e^{i \pi}\right)\right] d v \\
& -\frac{1}{2 \pi^{2}} \int_{0}^{i \infty} \frac{K_{1}(v \rho)}{K_{0}(v a)}\left[k_{0}\left(v \tau e^{-i \pi}\right)-K_{0}(v \tau)\right] d v \\
= & \frac{1}{2 \pi^{2}} \int_{-i \infty}^{0} \frac{K_{1}(v \rho)}{K_{0}(v a)} K_{0}\left(v \tau e^{i \pi}\right) d v-\frac{1}{2 \pi^{2}} \int_{0}^{i \infty} \frac{K_{1}(v \rho)}{K_{0}(v a)} K_{0}\left(v \tau e^{-i \pi}\right) d v \\
& -\frac{1}{2 \pi^{2}} \int_{-i \infty}^{0} \frac{K_{1}(v \rho)}{K_{0}(v a)} K_{0}(v \tau) d v+\frac{1}{2 \pi^{2}} \int_{0}^{i \infty} \frac{K_{1}(v \rho)}{K_{0}(v a)} K_{0}(v \tau) d v \tag{9}
\end{align*}
$$

We now deform the integration path of the first integral into $C_{3}+L_{-}$, that of the second integral into $C_{2}+L_{+}$, and those of the last two integrals into the positive real axis (Fig. 5). From the asymptotic forms of $K_{0}$ and $K_{1}$ it is easily seen that respective integrals over the infinite quarter circles $C_{1}, C_{2}, C_{3}$ and $C_{4}$ vanish for $\tau>0-a$. By making use of the formula ${ }^{7}$

$$
K_{\mu}\left(z e^{m \pi i}\right)=e^{-m \pi i} K_{\mu}(z)-\pi i \frac{\sin [\mu \pi}{\sin \mu \pi} I_{\mu}(z)
$$

the integrals over $L_{-}, I_{+}$and the real positive axis become

$$
\begin{align*}
\frac{z_{0} H_{\phi}}{v_{0}}= & -\frac{1}{2 \pi^{2}} \int_{0}^{\infty} \frac{K_{1}\left(v_{1} \rho\right)-\pi i I_{1}\left(v_{1} \rho\right)}{K_{0}\left(v_{1} a\right)+\pi i I_{0}\left(v_{1} a\right)} K_{0}\left(v_{1} \tau\right) d v_{1} \\
& -\frac{1}{2 \pi^{2}} \int_{0}^{\infty} \frac{K_{1}\left(v_{1} \rho\right)+\pi i I_{1}\left(v_{1} \rho\right)}{K_{0}\left(v_{1} a\right)-\pi i I_{0}\left(v_{1} a\right)} K_{0}\left(v_{1} \tau\right) d v_{1} \\
& +\frac{1}{\pi^{2}} \int_{0}^{\infty} \frac{K_{1}\left(v_{1} \rho\right)}{K_{0}\left(v_{1} a\right)} K_{0}\left(v_{1} \tau\right) d v_{1} \\
= & \int_{0}^{\infty} \frac{I_{0}\left(v_{1} a\right)\left[I_{0}\left(v_{1} a\right) K_{1}\left(v_{1} \rho\right)+I_{1}\left(v_{1} \rho\right) K_{0}\left(v_{1} a\right)\right]}{K_{0}\left(v_{1} a\right)\left[K_{0}^{2}\left(v_{1} a\right)+\pi^{2} I_{0}^{2}\left(v_{1} a\right)\right]} K_{0}\left(v_{1} \tau\right) d v_{1}, \text { for } \tau>\rho-a \tag{10}
\end{align*}
$$

Writing $u=v_{1} a$ and multiplying both sides by $r$ we finally arrive at the dimensionless form

$$
\begin{equation*}
\frac{r Z_{0} H_{\phi}}{v_{0}}=\frac{r}{a} \int_{0}^{\infty} \frac{I_{0}(u)\left[I_{0}(u) K_{1}(u \rho / a)+K_{0}(u) I_{1}(u \rho / a)\right]}{K_{0}(u)\left[K_{0}^{2}(u)+\pi^{2} I_{0}^{2}(u)\right]} K_{0}(u \tau / a) d u, \tag{11}
\end{equation*}
$$

$$
\text { for } \quad c t>\left((\rho-a)^{2}+z^{2}\right)^{1 / 2}
$$

This integral was numerically evaluated as function of $T$ for several values of $r$ and $\theta$, where $T$ is defined by

$$
T=\frac{c t-\left((\rho-a)^{2}+z^{2}\right)^{1 / 2}}{a}
$$

The results are presented in figures 6 through 13 . Setting $\rho=a$ in (11) and making use of the Wronskian relation among the modified Bessel functions we arrive at an alternative representation for the total current

$$
I(z, t)=\frac{4 v_{0}}{\pi Z_{0}} \int_{0}^{\infty} \frac{I_{0}(u) K_{0}(u T / a)}{K_{0}(u)\left[K_{0}^{2}(u)+\pi^{2} I_{0}^{2}(u)\right]} \frac{d u}{u}
$$

which was used for numerical computation in Ref. 3.

## IV. Remarks

It is expected that, for $\rho / a \gg 1$ and for some interval of the observation time $a T / c$, equation (11) should reduce to equation (4) of Ref. 1. Since equation (11) is valid for $\tau>p-a$, the statement that $\rho / a \gg 1$ also implies that $\tau / a \gg 1$. Using the appropriate asymptotic forms for $I_{1}(u p / a), K_{1}(u \rho / a)$ and $K_{0}(u \tau / a)$ in equation (1l) we obtain

$$
\begin{equation*}
\frac{r Z_{0} H_{\phi}}{v_{0}} \sim \frac{r}{2 \sqrt{\rho \tau}} \int_{0}^{\infty} \frac{I_{0}(u)}{K_{0}^{2}(u)+\pi^{2} I_{0}^{2}(u)} e^{-u\left(\frac{\tau-0}{a}\right)} \frac{d u}{u} \tag{12}
\end{equation*}
$$

For observation time much smaller than $\rho / c$, i.e., for $T \ll \rho / a$, we have ct $-r \ll \rho$. Then

$$
\begin{aligned}
\tau & =\left((c t)^{2}-z^{2}\right)^{1 / 2}=\left([(c t-r)+r]^{2}-z^{2}\right)^{1 / 2} \\
& =\left(p^{2}+2 r(c t-r)+(c t-r)^{2}\right)^{1 / 2} \\
& \approx \rho+\frac{c t-r}{\sin \theta}
\end{aligned}
$$

Insertion of this approximate expression of $\tau$ in (12) gives

$$
\begin{equation*}
\frac{r Z_{0}^{H_{\phi}}}{v_{0}}-\frac{1}{2 \sin \theta} \int_{0}^{\infty} \frac{I_{0}(u)}{K_{0}^{2}(u)+\pi^{2} I_{0}^{2}(u)} e^{-u\left(\frac{c t-r}{a \sin \theta}\right)} \frac{d u}{u} \tag{13}
\end{equation*}
$$

which is identical to the integral used in Ref. 1. Thus, the previous results are correct if $\rho / a \gg 1$ and $T \ll \rho / a$.

The curves labelled "r/a $\geq 10^{4}$ " in.figures 6 through 13 correspond to those obtained in Ref. 1. It appears that there is a difference between them in the early times. This apparent discrepancy is due to two different definitions of $T$. Let $T_{\text {old }}$ denote the $T$ used in Ref. 1 . Then, for p/a >> 1

$$
\begin{aligned}
T & =\frac{c t-\left((\rho-a)^{2}+z^{2}\right)^{1 / 2}}{a}-\frac{c t-(r-a)}{a}+\sin \theta-1 \\
& =T_{o l d}-(1-\sin \theta) .
\end{aligned}
$$

This equation accounts for the difference just mentioned.
Next, we shall deduce the limiting forms of equation (11) for large T and small T . From the definition of $\tau$, i.e.,

$$
\frac{\tau}{a}=\frac{\left((c t)^{2}-z^{2}\right)^{1 / 2}}{a}=\left\{T^{2}+2 T\left(\left(\frac{\rho}{a}-1\right)^{2}+\left(\frac{z}{a}\right)^{2}\right)^{1 / 2}+\left(\frac{\varrho}{a}-1\right)^{2}\right\}^{1 / 2},
$$

we see that $\tau / a \rightarrow \infty$ as $T \rightarrow \infty$, and that $\tau / a \rightarrow \rho / a-1$ as $T \rightarrow 0$.
Late time behavior of $r_{0} \mathrm{H}_{\phi} / \mathrm{v}_{\mathrm{o}}$
Substituting

$$
K_{0}(u \tau / a)=\int_{1}^{\infty} \frac{e^{-x u \tau / a}}{\sqrt{x^{2}-1}} d x
$$

into equation (11) and interchanging the order of integration we have

$$
\begin{equation*}
\frac{r Z_{0} H_{\phi}}{v_{0}}=\frac{r}{a} \int_{1}^{\infty} \frac{d x}{\sqrt{x^{2}-1}} \int_{0}^{\infty} \frac{I_{0}(u)\left[I_{0}(u) K_{1}(u \rho / a)+K_{0}(u) I_{1}(u \rho / a)\right]}{K_{0}(u)\left[K_{0}^{2}(u)+\pi^{2} I_{0}^{2}(u)\right]} e^{-u x \tau / a} d u . \tag{14}
\end{equation*}
$$

For large $x \tau / a$ the inner integral can be evaluated asymptotically in the same way as described in Ref. 1. Thus, (14) becomes

$$
\begin{align*}
& \left.\frac{{ }^{2}{ }_{0}{ }^{H} \phi}{v_{0}} \sim \frac{1}{2 \sin \theta} \int_{1}^{\infty} \frac{1}{\sqrt{x^{2}-1}} \frac{d x}{\left[\ln \frac{2 \tau}{\Gamma a}+\ln x\right]^{2}} \quad \text { (as } \tau / a \rightarrow \infty\right) \\
& \quad=\frac{1}{2 \sin \theta} \int_{1}^{\infty} \frac{d(\ln x)}{\left[\ln \frac{2 \tau}{\Gamma a}+\ln x\right]^{2}}\left(1-\frac{1}{x^{2}}\right)^{-1 / 2} \\
&  \tag{15}\\
& \sim \frac{1}{2 \sin \theta} \frac{1}{\ln \left(\frac{2 \tau}{\Gamma a}\right)} \quad, \quad \text { as } \tau / a \rightarrow \infty
\end{align*}
$$

where $\Gamma=1.7810 \cdots$. It is to be noted that the asymptotic formula (15) was derived under the condition $\rho / a<\tau / a \rightarrow \infty$. For $T>100$, one can use (15) to extend the curves, except the ones labelled "r/a $\geq 10^{4}$," in figures 10 through 13 , since the difference between the results calculated by (15) and those obtained by numerically computing equation (11) is less than $3 \%$ for $T \geq 100$.

Early time behavior of $r Z_{0} H_{\phi} / v_{o}$
Let $\tau / a-\rho / a+1=\varepsilon$. We wish to examine the limit of $r Z_{o} H_{\phi} / v_{o}$ as $\varepsilon \rightarrow 0$. Following the same procedure as in Ref. 1 we break equation (11) into two parts, viz.

$$
\frac{r Z_{0} H_{\phi}}{v_{o}}=\frac{r}{a} \int_{0}^{\delta}(\cdots) d u+\frac{r}{a} \int_{\delta}^{\infty}(\cdots) d u=I_{1}+I_{2}
$$

where $\delta$ is chosen in such a way that in evalating $I_{2}$ one can use the asymptotic forms for the modified Bessel functions. Thus

$$
\begin{equation*}
I_{2} \sim \frac{1}{\pi \sqrt{2 \pi}} \frac{r}{\sqrt{\rho \tau}} \int_{0}^{\infty}\left\{e^{-u(\rho-a) / a}+e^{u(\rho-a) / a}\right\} \frac{e^{-u \varepsilon-u(\rho-a) / a}}{\sqrt{u}} d u \tag{16}
\end{equation*}
$$

If $\rho>a$ and $(\rho-a) / a \gg \varepsilon \rightarrow 0$, then (16) gives

$$
\begin{equation*}
I_{2}-\frac{1}{\pi \sqrt{2}} \frac{r}{\sqrt{\rho(\rho-a)}} \frac{1}{\sqrt{\varepsilon}} \tag{17a}
\end{equation*}
$$

If $\rho=a$ and $\varepsilon \rightarrow 0$, then (16) gives

$$
\begin{equation*}
I_{2}-\frac{\sqrt{2}}{\pi}\left(a^{2}+z^{2}\right)^{\frac{1}{2}}\left((c t)^{2}-z^{2}\right)^{-\frac{1}{2}} \tag{17b}
\end{equation*}
$$

$I_{1}$ is easily seen to be negligible compared to $I_{2}$ when $\varepsilon \rightarrow 0$. The curves in figures 6 through 9 indeed have the behavior described by (17) for small T. Using (17b) one can immediately deduce that the total current $I(z, t)$ takes the form

$$
I(z, t)-\frac{v_{0}}{Z_{0}} \frac{2 \sqrt{2} a}{\left((c t)^{2}-z^{2}\right)^{\frac{1}{2}}} \quad, \quad \text { as } c t-z \rightarrow 0+
$$

Before concluding this note, two additional remarks are in order, Tr, coughout this note we have treated exclusively the magnetic field $H_{\phi}$, Frting aside the non-vanishing components $E_{r}$ and $E_{\theta}$ of the electric told. Of course, $E_{r}$ and $E_{\theta}$ are obtainable from $H_{\phi}$ via Maxwell's
equations; but an extra integration over time is required, thus making $E_{r}$ and $E_{\theta}$ expressible in terms of double integrals. Very far away from the antenna, however, we have- $E_{\theta}=Z_{o} H_{\phi}$, i.e., $E_{\theta}$ and $Z_{o} H_{\phi}$ have identical waveforms. The reason that $H_{\phi}$ can be expressed as a single integral is that we have considered a step-function excitation which allows one integral of the double integral (i.e., the inner integral of (4)) to be evaluated explicitly. The second remark is that although we have treated an infinite antenna in this note, the results are still valid for an antenna of total length $2 h$ if the observation time $a T / c<h / c+\left(R_{2}-R_{1}\right) / c, R_{1}$ and $R_{2}$ being respectively the distance from the observation point to the excitation point and to the nearer end of the antenna.

## References

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Figure 1. Infinite cylindrical antenna with a gap generator.


Figure 2. Branch of $v=\sqrt{\zeta^{2}+\overline{p^{2}}}: \nu=p$ at $\zeta=0$.


Figure 3. Path of Integration


Figure 4. Branch of $\zeta=\sqrt{\nu^{2}-p^{2}}: \zeta=1 p$ at $\dot{v}=0$ if $z>0$, and $\zeta=-$ ip at $\nu=0$ if $z<0$.


Figure 5. The branch where $|\arg v|<\pi$.


Figure 6. Magnetic-field waveforms for a step-function excitation.


Figure 7. Magnetic-field waveforms for a step-function excitation,


Figure 8. Magnetic-field waveforms for a step-function excitation.


Figure 9. Magnetic-field waveforms for a step-function excitation.


Figure 10. Magnetic-field waveforms for a step-function excitation.


Figure 11. Magnetic-field waveforms for a step-function excitation.


Figure 12. Magnetic-field waveforms for a step-function excitation.


Figure 13. Magnetic-fleld waveforms for a step-function excitation.

